# Meshless Radial Basis Functions Method for Solving Hallen's Integral Equation 

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#### Abstract

This paper introduced a meshless method based on radial basis function (RBF) interpolation to solve Hallen's integral equation (HIE) of the thin wire. The unknown current $I_{z}(z)$ is interpolated by RBF at the center nodes and point matching method is applied to HIE at the collocation nodes. To validate the present method, the input impedance and induced current of dipole antenna are computed with the $r^{5}-\mathrm{RBF}$ and Wu's RBF, respectively. The results show that the present method is a steady numerical approach for solving HIE.


Index Terms-Hallen's integral equation, meshless method, point matching method, radial basis functions.

## I. INTRODUCTION

In the past several decades, various numerical techniques have been used to solve Hallen's integral equation (HIE) and evaluate electromagnetic field, induced current distribution, and input impedance of thin linear antenna. Mei firstly proposed classical moment method (MOM) to solve HIE [1]. Now, various advanced numerical approaches were applied to HIE, such as high accurate computation[2], hybrid procedure[4], Galerkin's methods [5], high-order numerical solution [6], entire-domain basis functions in Galerkin's methods [7], and some combined algorithm with MOM[3].

The techniques mentioned above are grid-based or mesh-based ones. In recent years, meshfree or meshless methods (MLMs) based on a set of nodes scattering within the problem domain have gained much attention in the engineering communities [8] and significantly developed in the electromagnetic engineering area [9]-[11]. Nicomedes proposed the improve Moving Least Square to solve the combined field integral equation [12]. Galerkin-Bubnov Integral Equation Method [13] was used to solve time-domain HIE. In this paper, we introduce a meshless method based on radial basis function interpolation (MLM-RBF) to solve HIE. RBF interpolation is a powerful technique that was first proposed by Kansa in 1990 to solve partial difference equations (PDEs) [14]. MLM-RBF is a numerical method by which unknown functions of PDEs or integral equations are interpolated at the scattered nodes and
point matching method is applied to the equations at the collocation nodes

Section II describes the MLM-RBF formulation of HIE. It also presents the process of impedance matrix calculation. In Section III, the numerical results using two different RBFs are discussed in detail. Conclusion is given in Section IV.

## II. Formulation

Figure 1 shows a perfectly conducting long and $\hat{z}$ -oriented thin wire of $L$ in length whose radius $R_{0}$ is much less than $L$ and wavelength $\lambda$. The HIE of the thin and straight wire can be expressed as [15]

$$
\begin{equation*}
E_{z}^{i}(z)=\frac{j}{\omega \varepsilon}\left[\frac{\partial}{\partial z^{2}}+k^{2}\right] \int_{-L / 2}^{L / 2} I_{z}\left(z^{\prime}\right) \frac{e^{-j k R}}{4 \pi R} d z^{\prime} \tag{1}
\end{equation*}
$$

where $R=\sqrt{\left(z-z^{\prime}\right)^{2}+a^{2}}$ and $k$ represents propagation constant. Through a series of processing steps [15], the above equation can be simplified as

$$
\begin{align*}
& \int_{-L / 2}^{L / 2} I_{z}\left(z^{\prime}\right) \frac{e^{-j k R}}{4 \pi R} d z^{\prime}=D_{1} e^{j k z}+D_{2} e^{-j k z} \\
&+\frac{1}{2 \eta} \int_{-L / 2}^{L / 2} e^{-j k\left|z-z^{\prime}\right|} E_{z}^{i}\left(z^{\prime}\right) d z^{\prime} \tag{2}
\end{align*}
$$

where $\eta$ is wave impedance, $D_{1}$ and $D_{2}$ are unknown constants.

(a)

(b)

Fig. 1. Model of thin wire (a) and node distribution (b).
The unknown function $I_{z}$ in (2) can be interpolated approximately by a series of RBF:

$$
\begin{equation*}
I_{z}(z) \approx \sum_{I=1}^{N} \phi_{I}(z) a_{I}=\sum_{I=1}^{N} \phi\left(\left|z-z_{I}\right|\right) a_{I}, \quad z \in[-L / 2, L / 2] \tag{3}
\end{equation*}
$$

where $\phi_{I}(\boldsymbol{r})$ is the radial basis function centered at a set of independent points $\boldsymbol{r}_{1}, \cdots, \boldsymbol{r}_{I}, \cdots, \boldsymbol{r}_{N} \in \Omega$ (also called center nodes, see Fig. 1 (b)). $a_{I}$ are unknown coefficients to be computed.

Substituting (3) into (2), we get

$$
\begin{align*}
& \sum_{I=1}^{N} a_{I} \int_{L_{I}} \phi_{I}\left(z^{\prime}\right) \frac{e^{-j k R}}{4 \pi R} d z^{\prime}=D_{1} e^{j k z}+D_{2} e^{-j k z}  \tag{4}\\
&+\frac{1}{2 \eta} \int_{-L / 2}^{L / 2} e^{-j k\left|z-z^{\prime}\right|} E_{z}^{i}\left(z^{\prime}\right) d z^{\prime}
\end{align*}
$$

where $L_{I}$ is the integral domain at the center node $z_{I}$ and $\phi_{I}\left(z^{\prime}\right)=\phi\left(\left|z^{\prime}-z_{I}\right|\right)$. Then, point-matching method (PMM) is applied to the above equation at a set of collocation nodes $z_{1}, \cdots, z_{J}, \cdots, z_{M}(M \geq N)$ (see Fig. 1 (b)) which distribute on the wire surface. Thus, we get

$$
\begin{align*}
\sum_{I=1}^{N} a_{I} \int_{L_{I}} \phi\left(\left|z^{\prime}-z_{I}\right|\right) & \frac{e^{-j k R_{J}}}{4 \pi R_{J}} d z^{\prime}=D_{1} e^{j k z_{J}}+D_{2} e^{-j k z_{J}}  \tag{5}\\
+ & \frac{1}{2 \eta} \int_{-L / 2}^{L / 2} e^{-j k\left|z_{J}-z^{\prime}\right|} E_{z}^{i}\left(z^{\prime}\right) d z^{\prime}
\end{align*}
$$

where $R_{J}=\sqrt{\left(z_{J}-z^{\prime}\right)^{2}+a^{2}}$. The resulting matrix of the above equation is of the form

$$
\begin{equation*}
\mathbf{Z} \mathbf{a}=\left[\mathbf{s}_{1}, \mathbf{s}_{2}\right]\left[D_{1}, D_{2}\right]^{T}+\mathbf{b} \tag{6}
\end{equation*}
$$

where the elements of impedance matrix $\mathbf{Z}$ are

$$
\begin{equation*}
z_{I J}=\int_{L_{I}} \phi\left(\left|z^{\prime}-z_{I}\right|\right) \frac{e^{-j k R_{J}}}{4 \pi R_{J}} d z^{\prime} \tag{7}
\end{equation*}
$$

and the vector elements of right-hand side of (6)

$$
\begin{align*}
& s_{1 J}=e^{j k z_{J}}, s_{2 J}=e^{-j k z_{J}} \\
& b_{J}=\frac{1}{2 \eta} \int_{-L / 2}^{L / 2} e^{-j k\left|z_{J}-z^{\prime}\right|} E_{z}^{i}\left(z^{\prime}\right) d z^{\prime} \tag{8}
\end{align*}
$$

## A. Calculation of unknown constant $D_{1}$ and $D_{\mathbf{2}}$

To obtain the unknown vector a in (6), the constant $D_{1}$ and $D_{2}$ should be determined first. This can be done by using the current boundary condition at the ends of the wire, i.e., $I_{z}(-L / 2)=I_{z}(L / 2)=0$. From $(6)$, we have

$$
\begin{equation*}
\mathbf{a}=\mathbf{Z}^{-1}\left[\mathbf{s}_{1}, \mathbf{s}_{2}\right]\left[D_{1}, D_{2}\right]^{T}+\mathbf{Z}^{-1} \mathbf{b} \tag{9}
\end{equation*}
$$

Defining $[\mathbf{U}]=\left[\mathbf{u}_{1}^{T}, \mathbf{u}_{2}^{T}\right]$, where $\mathbf{u}_{1}^{T}=[1,0, \ldots, 0]$ and $\mathbf{u}_{2}^{T}$ $=[0, \ldots, 0,1]$ and multiplying both sides of (9) by $[\mathbf{U}]^{T}$, we get

$$
\begin{equation*}
[\mathbf{U}]^{T} \mathbf{a}=[\mathbf{U}]^{T} \mathbf{Z}^{-1}\left[\mathbf{s}_{1}, \mathbf{s}_{2}\right]\left[D_{1}, D_{2}\right]^{T}+[\mathbf{U}]^{T} \mathbf{Z}^{-1} \mathbf{b}=0 \tag{10}
\end{equation*}
$$

Solving (10), we get

$$
\begin{equation*}
\left[D_{1}, D_{2}\right]^{T}=-\left[[\mathbf{U}]^{T} \mathbf{Z}^{-1}\left[\mathbf{s}_{1}, \mathbf{s}_{2}\right]\right]^{-1}[\mathbf{U}]^{T} \mathbf{Z}^{-1} \mathbf{b} \tag{11}
\end{equation*}
$$

## B. Calculation of matrix element

When the collocation node $z_{J}$ does not locate in the range of the supported domain centered at $z_{I}$, the matrix elements of (7) can be computed via an $Q$-point numerical quadrature [15]:

$$
\begin{equation*}
z_{I J}=\sum_{q=1}^{Q} w_{q} \phi_{I}\left(\left|z_{I q}-z_{I}\right|\right) \frac{e^{-j k R_{J_{-} q q}}}{4 \pi R_{J_{-} q}}, \quad I \neq J \tag{12}
\end{equation*}
$$

where $\quad R_{J_{-} q q}=\sqrt{\left(z_{J}-z_{J_{-} I q}\right)^{2}+a^{2}}$.
When $z_{J}$ locates in the range of the supported domain centered at $z_{I}$, as shown in Fig. 2, there exists the quasisingular integral in (7). To improve the integral accuracy, a very small domain $\Delta_{z}$ centered at $z_{J}$ is extracted from $L_{I}$ of (7). Thus, there exist three integral domains in $L_{I}$ : $\left[Z_{I}-d_{m I}, \quad Z_{J}-\Delta_{Z} / 2\right], \quad\left[Z_{J}-\Delta_{z} / 2, \quad z_{J}+\Delta_{z} / 2\right]$, and $\left[z_{J}+\Delta_{z} / 2\right.$, $\left.z_{I}+d_{m I}\right]$ (see Fig.2), where $d_{m I}$ is the radius of supported domain of RBF centered at $z_{I}$. In $\Delta_{z}$, the integral item $\phi\left(\left|z^{\prime}-z_{I}\right|\right)$ in (7) is treated as a constant value $\phi\left(\left|z_{J}-z_{I}\right|\right)$ and the Green's function item is expanded by the small-argument approximation [15]. Thus, (7) in the integral domain $\Delta_{z}$ can be rewritten as:

$$
\begin{align*}
& \int_{-\Delta_{z} / 2}^{\Delta_{z} / 2} \phi\left(\left|z^{\prime}-z_{I}\right|\right) \frac{1-j k R_{J}}{4 \pi R_{J}} d z^{\prime}  \tag{13}\\
& =\phi\left(\left|z_{J}-z_{I}\right|\right)\left[\frac{1}{4 \pi} \ln \left(\frac{\sqrt{1+4 a^{2} / \Delta_{z}^{2}}+1}{\sqrt{1+4 a^{2} / \Delta_{z}^{2}}-1}\right)-\frac{j k \Delta_{z}}{4 \pi}\right], I=J
\end{align*}
$$

In other two domains, (7) is also computed by the $Q$-point numerical quadrature (12).

Each element in (7) needs to be calculated with the $Q$-point numerical quadrature, not a simple expression in MOM [15]. Thus, the amount of calculation of MLM-RBF is more than that of MOM in solving HIE.


Fig. 2. Collocation node $z_{J}$ located in the range of the supported domain centered at $Z_{I}$

From (6), the unknown coefficient vector a can be solved. Then substituting a into(3), we can get the current distribution of the thin wire.

## III. NUMERICAL RESULTS

In order to validate the present method, the input impedance and induced current distribution of a thin wire are calculated by MLM-RBF. Here, a delta-gap
source $E_{z}^{i}\left(z^{\prime}\right)=\delta\left(z^{\prime}\right)$ at the center of the wire is adopted, as shown in Fig. 1(a). The length and radius of the wire are set as $L=\lambda / 2$ and $a=10^{-3} \lambda$, respectively. Uniform node distribution is adopted on the wire axis and the distance between nodes is $h$. To analyze the accuracy of the present numerical algorithm, the results of MLM-RBF are compared with those of mesh-based MOM on the condition that the node distribution (grid distribution) is the same. In this work, two different kinds of MOM are taken as referenced methods, which are PMM with pulse basis function and Galerkin's method with triangle basis function. The former is directly used to solve HIE and this process is called Hallen/Pulse approach. The later is used to solve electric field integral equation (EFIE) of arbitrarily shaped thin wired (ATW) model [15] and this process is called ATW/Triangle approach.

There are many different types of RBFs. Here, two typical RBFs are chosen. One is the quintic RBF:

$$
\begin{equation*}
\phi_{I}(\boldsymbol{r})=r^{5} \tag{14}
\end{equation*}
$$

which is a globally supported RBF without shape parameter. Another is the compactly supported RBF given by Wu [16]:

$$
\begin{equation*}
\phi_{I}(\boldsymbol{r})=(1-r)_{+}^{6}\left(6+36 r+82 r^{2}+72 r^{3}+30 r^{4}+5 r^{5}\right) \tag{15}
\end{equation*}
$$

where $r=\left\|\boldsymbol{r}-\boldsymbol{r}_{I}\right\| / d_{m I}$, and

$$
(1-r)_{+}=\left\{\begin{array}{lc}
1-r & 0 \leq r \leq 1  \tag{16}\\
0 & \text { other }
\end{array}\right.
$$

First, we compare the rates of convergence of the input impedance versus the node number by MLM-RBF with those by referenced methods. Figure 3 (a) shows the results of $\boldsymbol{r}^{5}$ RBF-based MLM (MLM-r ${ }^{5}$-RBF). We can see that, like ATW/Triangle approach, the input impedance of MLM-RBF converges fast to a stable value when the node number is only 12 (i.e. 24 nodes per wavelength). In sharp contrast to $r^{5}-\mathrm{RBF}$ case, the input impedance of the Hallen/Pulse approach converges slowly: more than 200 segments are needed to obtain a good convergence. However, the results of MLM- $r^{5}-$ RBF could be inaccurate when node number exceeds 90 . This is because the condition number of impedance matrix constructed by $r^{5}$ RBF is too large (more than $10^{14}$ ) when node number exceeds 90 . The $r^{5}$ RBF is a power function, its value at the center point is zero. Its conforming impedance matrix is not strictly diagonally dominant matrices that condition number is very large.

In Wu's RBF case ( $d_{m I}=2.4^{*} h$ ), it can be seen that the input impedance converges more slowly than in $r^{5}$ RBF case, but still faster than Hallen/Pulse approach, as shown in Fig. 3 (b). The input resistance computed by Wu's RBF-based MLM (MLM-Wu-RBF) is in good agreement with that by ATW/Triangle approach when node number exceeds 50 . For the input reactance of

MLM-Wu-RBF, 100 nodes are needed to obtain good convergence results. However, 300 segments are needed for Hallen/Pulse approach. Due to the compactly supported property of Wu's RBF, the generated impedance matrix is strip and sparse. The condition number of the impedance matrix is only 58 when node number reaches 250 , which is far less than that of the impedance matrix of $r^{5} \mathrm{RBF}$ case.

In Wu's RBF case, besides the node number $N$, there is another parameter $d_{m I}$ to influence the calculation accuracy. Figure 4 shows the input impedance versus $d_{m I}$ of Wu's RBF. From the figure, we can see that the input impedance increases quickly to the peak-value and then decreases slowly as $d_{m I}$ increases. In addition, there exists a range of steady $d_{m I}$ within which the relative errors of peak-value are small. For example, when $N=101$, the relative error of the peak-value of input resistance is under $1.6 \%$ when $d_{m I}$ ranges from $1.8^{*} h$ to $6^{*} h$. From the figure, we can also see that the range of steady $d_{m I}$ widens as the node number increases. General, the $d_{m I}$ parameter of Wu's RBF in HIE is set the $2 * h$ to $5^{*} h$ that the calculation accuracy is good.


Fig. 3. Input impedance of a $\lambda / 2$ dipole for (a) $r^{5} \mathrm{RBF}$ and (b) Wu's RBF.


Fig. 4. Input impedance versus supported domain $d_{m I}$ of Wu's RBF.

Then, we compare the induced current distributions between MLM-RBF and reference methods. Figure 5 shows the induced current in $r^{5}$ RBF case and induced current versus the $d_{m I}$ in Wu's RBF case when $N=41$. In $r^{5}$ RBF case, the maximum error relative to ATW/ Triangle approach at the center node is $4 \%$. In Wu's RBF case, the maximum error at the center node is $8 \%$ when $d_{m I}$ ranges from $1.8^{*} h$ to $6^{*} h$. When $d_{m I}=2.7^{*} h$, $4.2 * h$, and $5.7^{*} h$, the current curves are close to those of ATW/Triangle approach. However, when $d_{m I}$ is not within the steady range (from $1.8^{*} h$ to $6^{*} h$ ), there exist great errors. For example, when $d_{m I}=1.2 * h$, the maximum error is $36 \%$ at the center node.


Fig. 5. Induced current distribution on a $\lambda / 2$ dipole (node number is 41).

Finally, we consider the generalization of the present method. Taking Wu's RBF for example, we suppose that the $d_{m I}$ is set $2.4^{*} h$ and a node number per wavelength is at approximately 15 , and then the input impedance versus the dipole length ranging from $0.2 \lambda$ to $3.5 \lambda$ is computed; the results are shown in Fig. 6. The results of MLM-Wu-RBF are in good agreement with those of ATW/Triangle approach almost at every data point, which seems to show that MLM-Wu-RBF is a feasible and stable algorithm to solving HIE when $d_{m I}$ is in the steady range.


Fig. 6. Input impedance versus dipole length in Wu's RBF case.

## IV. CONCLUSION

In this letter, MLM-RBF is applied to solve HIE of thin wire. The results show that the convergent rates of MLM-RBF are faster than those of MOM. In addition, there exists a steady range of $d_{m I}$ for Wu's RBF within which the results reach certain accuracy. And the steady range of parameter $d_{m I}$ widens as the node number increases. The induced current distributions of $r^{5} \mathrm{RBF}$ and Wu's RBF within the steady-range parameter $d_{m I}$ are in agreement with the referenced methods. For the $r^{5}$ RBF case, the condition number of impedance matrix is too large that some problems cannot be solved. For the Wu's RBF case, when the sample nodes and $d_{m I}$ are set as certain values, the impedances varying with the length of wire are also in agreement with the referenced results, which seems that MLM-RBF can be a general algorithm to computing HIE. But the calculation burden of filling its matrix is somewhat heavier than that of MOM.

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