Improved and Easy-to-implement HFSS-MATLAB Interface without VBA Scripts: An Insightful Application to the Numerical Design of Patch Antennas

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Abstract – An improved and easy-to-implement HFSS-MATLAB interface is presented. Because the interface is realized without the use of VBA scripts, it is easier to implement for beginners and practitioners. This advantage allows more dissemination of the code in the HFSS community. The interface is applied to the numerical design of a patch antenna, showing the capabilities it enables. Practical details about the implementation are provided, enabling the reader to implement the interface on their own.

Index Terms – application programming interface, HFSS, hierarchical optimization, MATLAB, patch antenna.

I. INTRODUCTION

Modern programs for computer-aided design (CAD) are extremely useful tools for the design of complex structures. However, they are difficult to manage when they have to be interfaced with other software or when complex operations are necessary [1, 2].

In order to manage complex operations involving CAD software in a straightforward way, it is of paramount importance to be able to interface CAD software with a numeric computing environment (NCE). In the following, we refer to HFSS [3] and MATLAB [4].

The development of an HFSS-MATLAB interface is not new. It is described in [5–8], and a library for the interface between MATLAB and HFSS is available online [9]. In [1, 2], FEKO [10] is interfaced with MAT-LAB. Python has also been used recently to launch EM simulators [11, 12]. However, the mentioned works use the Visual Basic for Applications (VBA) scripting language to interface HFSS and MATLAB. VBA scripts require large libraries, since each feature in the HFSS model requires a specific command with a specific syntax. Then, even if HFSS commands can be recorded to a script exploiting a useful feature of HFSS [6], writing a script is a slow and tedious task, especially for beginners. Another possibility to interface HFSS and MATLAB is to call the latter during the execution of the former. However, this interface is much less flexible than the one in which MATLAB drives HFSS. Not to be forgotten, students and experienced designers can feel pain when they have to learn a further programming language [13].

This paper presents and describes an improved and easy-to-implement HFSS-MATLAB interface that makes no use of VBA scripts. To achieve this goal, variables are updated in the ASCII file describing the HFSS model to simulate. Practical details are provided for the implementation of the application programming interface (API). Moreover, for easier reproducibility of the API, working examples are also available at [14]. Thanks to the API, there is no need to learn VBA to script HFSS. This CAD is then treated like a black box that returns the output of a simulation once it is called from MAT-LAB. The working principles of the API are presented in a practical example: the numerical design of a patch antenna resonating at 2 GHz.

II. DESIGN EXAMPLE

The example considered for illustrating the proposed interface is the numerical design of a rectangular patch antenna working at $f_0 = 2 \text{ GHz}$. The substrate of the antenna is characterized by a height of 1.6 mm, a metallization thickness of 0.035 mm, and a relative dielectric constant of 2.2. The technical drawing of the proposed antenna is depicted in Fig. 1. The patch is characterized by a width W and a length L. The feed is a $\lambda/4$ transformer whose length is a. To have more degrees of freedom, the transformer has a trapezoidal shape whose bases are M - 2b and M - 2c, where M = 4.943 mm, the width of the microstrip with a 50 Ω characteristic impedance. The distance between the patch and the sides of the substrate is $L_e = 8 \text{ mm}$ and the length of the 50 Ω microstrip is $L_m = 10$ mm. In the following, only parameters a, b, c, W, and L are variable, the others being constants.

An analytical design procedure for rectangular patch antennas is possible [15], and the values of the geometrical parameters for this design are listed in Table 1.

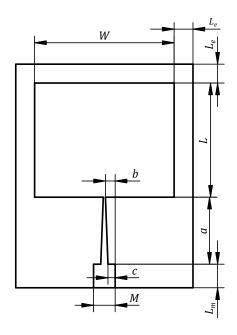


Fig. 1. Technical drawing of the patch antenna.

Table 1: Variable history (dimensions in millimeters, abbreviation a.a. stands for *as above*)

	Variables				
	L	W	а	b	С
Min	46	57	26	1.500	1.500
Max	50	61	32	2.370	2.370
Anal.	49.830	59.290	28.510	2.070	2.070
Opt. (i)	48.472	a.a.	a.a.	a.a.	a.a.
Opt. (ii)	a.a.	59.225	28.440	2.014	1.999

However, once the geometrical values from the analytical design are simulated, the antenna results do not match them at the desired working frequency, as shown in Fig. 2. The resonant frequency f_r (the frequency at which the minimum of the return loss occurs), the minimum of the return loss $|S_{11}|_m$ and the return loss at $f_0 = 2$ GHz, $|S_{11}(f_0)|$, are gathered in Table 2.

To have an antenna working at the desired frequency, an optimization is performed. Since the magnitude of the reflection coefficient is not a smooth function of the geometrical parameters [16], it is not wise to consider a unique goal for the optimization of the return loss. Then, the problem is tackled by means of a hierarchical optimization with these two goals:

$$\min_{L} (f_r - f_0)^2 \tag{1a}$$

$$\min_{a,b,c,W} |S_{11}|_m,\tag{1b}$$

where min stands for minimize. The reasons behind the definitions of these two optimizations derive from the theory of the problem. Indeed, it is known from theory

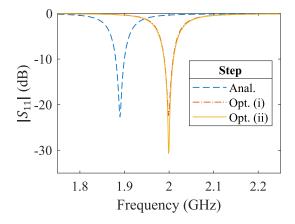


Fig. 2. Magnitude of S_{11} for the patch antenna during the different steps of the design.

Table 2: Result summary

Step	fr (GHz)	$ S_{11} _m (\mathrm{dB})$	$ S_{11}(f_0) $ (dB)
Anal.	1.890	-22.68	-0.35
Opt. (i)	1.999	-22.37	-21.83
Opt. (ii)	1.999	-30.70	-29.99

[15] that a) the resonant frequency depends *primarily* on the patch length, and b) matching depends *primarily* on the feed dimensions and patch width. Then the two optimizations of the hierarchical optimization are (1a) for point a and (1b) for point b. Note that while improving matching in (1b) we do not care about the resonant frequency of the antenna, assuming that it does not change remarkably. However, if the change in the resonant frequency after solving (1b) is remarkable, then optimization (1a) can be repeated to re-center the resonant frequency at the desired value.

For the above optimizations, the MATLAB optimization functions are *fminbnd* for (1a), and *fmincon* for (1b). Function *fminbnd* is especially useful for minimization problems with a single variable. As starting point for the hierarchical optimization, the analytical design is considered. The minimum and maximum values for the variables being optimized are listed in Table 1.

III. DESCRIPTION OF THE API

In the following, the filenames indicated in Table 3 are considered. Obviously, only the file extension must be the one indicated while the filename could be different, provided that all occurrences change accordingly.

The MATLAB commands are in *HFSS_API.m.* The HFSS model to simulate is *base.aedt*, while *base.txt* is the same as *base.aedt*, but with the variables substituted by univocal signposts. The file *modified.aedt* is the HFSS model to simulate with updated variables. Eventually,

Filename	Description		
HFSS_API.m	MATLAB script for the interface		
base.aedt	Model to simulate		
base.txt	Model with signposts		
modified.aedt	Model with updated variables		
ExportToFile.py	Python script for data extraction		
res.csv	Exported results		

Table 3: Files for the API

ExportToFile.py is the Python script for the export of the results and *res.csv* the exported results.

The flow chart for the proposed API is presented in Fig. 3. The proposed API is made of steps to be done once, called *Preliminary steps*, and steps that have to be done before each simulation, called *Steps to be repeated*. The preliminary steps are done manually by the designer, while the API automatically performs the others. Furthermore, the blocks with rounded corners refer to the steps performed in MATLAB, while those without rounded corners to those of the API.

A. Preliminary steps

The preliminary steps are:

- build the model in HFSS and save it as *base.aedt*;
- copy the previous file and open it as a text file. Substitute the numerical values of the variables to be varied with unique character combinations ('signposts', one for each variable), and save the file as *base.txt*;
- generate the file *ExportToFile.py* to export the results of the simulation.

Since all setups are run by the command used to execute the simulations, the designer, while preparing the HFSS model, should follow these directions: a) insert only one design, called *Design* in the following; b) insert only the required setups.

Here is the part of file *base.txt* defining the variables of the design: the signposts inserted to substitute for the variables are shown in bold:

\$begin 'Properties'

```
VariableProp('A', 'UD', '', '1A1Amm')
VariableProp('B', 'UD', '', '1B1Bmm')
VariableProp('a', 'UD', '', '2A2Amm')
VariableProp('b', 'UD', '', '2B2Bmm')
VariableProp('c', 'UD', '', '2C2Cmm')
VariableProp('tc', 'UD', '', '1.6mm')
VariableProp('tc', 'UD', '', '0.035mm')
VariableProp('Le', 'UD', '', '8mm')
VariableProp('Lm', 'UD', '', '4.942869528525mm')
$end 'Properties'.
```

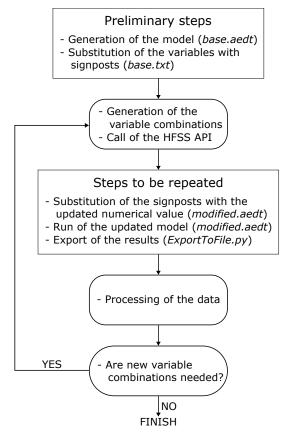


Fig. 3. Flow chart of the proposed API. The rectangles with rounded corners refer to the steps performed in MATLAB, while those without rounded corners relate to the proposed API.

Here is the Python file *ExportToFile.py* to export the results of the simulation:

oDesktop.RestoreWindow() oProject = oDesktop.SetActiveProject("Modified") oDesign = oProject.SetActiveDesign("Design") oModule = oDesign.GetModule("ReportSetup") oModule.UpdateReports(["S11mag"]) oModule.ExportToFile("S11mag", "res.csv"),

where *Design* is the name of the design in *modified.aedt* and *S11mag* is the name of the report displaying the results. The file *ExportToFile.py* could even be generated automatically in MATLAB.

B. Steps to be repeated

The steps to be repeated for each parameter combination request by the MATLAB script are:

• read file *base.txt* containing signposts, substitute each signpost with the numerical values indicated by the MATLAB script, and save the new file as *modified.aedt*;

- run file *modified.aedt* to simulate the model;
- run file *ExportToFile.py* to export results;
- read the results exported in file res.csv.

While substituting the numerical values with signposts, the designer must be aware of the right correspondence between the substituted variables and the actual variables in the model. Therefore, it is helpful to note a correspondence table while inserting the signposts. For example, after having substituted the numerical variables, the file *modified.aedt* appears as

\$begin 'Properties'

```
VariableProp('L', 'UD', '', '48.47213595500mm')
VariableProp('W', 'UD', '', '59.22459629087mm')
VariableProp('a', 'UD', '', '28.44027653740mm')
VariableProp('b', 'UD', '', '2.013573376324mm')
VariableProp('c', 'UD', '', '1.999106250004mm')
VariableProp('ts', 'UD', '', '1.6mm')
VariableProp('tc', 'UD', '', '1.6mm')
VariableProp('tc', 'UD', '', '1.6mm')
VariableProp('Le', 'UD', '', '1.6mm')
VariableProp('Le', 'UD', '', '1.0mm')
VariableProp('M', 'UD', '', '4.942869528525mm')
$end 'Properties'.
```

The MATLAB command that executes a string in the command window is *system(StringToExecute)*. The string for simulating the HFSS model is

"PathExe\ansysedt.exe"	/Ng	/BatchSolve
<i>"Path\modified.aedt",</i>		

while the string for exporting the results is

"PathExe\ansysedt.exe" /Ng /BatchExtract "Path\ExportToFile.py" "Path\modified.aedt",

where *ansysedt.exe* is the executable for HFSS, *PathExe* is the folder where the executable file *ansysedt.exe* is stored, /Ng is the setting enabling the non-graphical mode, and *Path* is the folder where the files listed in Table 3 are saved.

IV. RESULTS

After running optimizations (1a) and (1b), the results for the reflection coefficient are presented in Fig. 2, and the values of the variables are listed in Table 1. Data summarizing the optimization are gathered in Table 2.

We note that it is sufficient to operate only on the length of the patch to have it resonating at the desired frequency. Additionally, optimization (1b) on the other parameters successfully improves matching without affecting the resonant frequency. Eventually, the first optimization requires only 2 function evaluations while the second requires 13, thus proving the effectiveness of the hierarchical optimization over indiscriminate global optimization algorithms like genetic ones [17, 18].

V. CONCLUSIONS

A useful interface between a CAD software, HFSS, and a software for technical computing, MATLAB, is outlined. Unlike other approaches performing the same task, the proposed one makes no use of VBA scripts to drive HFSS, hence being easier to implement and allowing the execution of simulations in non-graphical mode.

A glance into the interesting features enabled by this interface is provided by means of an example: the tuning of a resonant patch antenna. Despite this rather simple problem, it shows how the proposed API interface can realize complex procedures. Indeed, without the API, the designer would launch the different optimizations manually, with a high risk of errors and the need to keep up with the execution. On the contrary, with the proposed API, all steps of the hierarchical optimization can be handled automatically in MATLAB with much more flexibility.

Even though this interface is developed to drive HFSS, its working principles are of general validity and can be adapted to drive other simulators or software. For instance, the author applied the proposed method to drive GPT [19], a code for particle simulations.

Here what we learned from this lesson. Firstly, for the happiness of many, there is no need to learn VBA. Secondly, despite the computation capabilities we are experiencing nowadays, a good knowledge of the theory behind what we are studying is fundamental. The analyzed example shows how a hierarchical optimization approach can tune a patch antenna with only few 3D fullwave simulations.

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