# Analysis and Design of Quad-Band Four-Section Transmission Line Impedance Transformer

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*Abstract* – The design of four-section transmission line matching transformer, operating at four arbitrary frequencies, is presented. Standard transmission line theory is used to obtain a closed form expression that is solved using particle swarm optimization technique to find the required transformer parameters (lengths, and characteristic impedances). Different examples are presented which validate the design approach. To further validate the analysis and design approach, a microstrip line four-section quad-band transmission line transformer is designed, analyzed, fabricated and measured.

# I. INTRODUCTION

With the advent of multi-band operation in wireless communication systems, it becomes essential to have matching transformers that operate at several frequencies. Recently, several papers have been published in which different techniques were proposed to design dualfrequency matching transformers [1-4]. In [1], a  $\lambda/4$  shorted stub was added to a conventional single-shuntstub matching network that enabled impedance matching at two separate frequencies simultaneously. In [2], a novel dual-band two-section transmission line transformer (TLT) was proposed and simple design equations for the impedances and lengths of the two sections were derived in [3]. In [4], an extension of this dual-band TLT to match complex impedances was presented and applied to wideband high-frequency amplifiers. Very recently, a triple-band three-section TLT, extended from the twosection TLT concept, was designed and analyzed in [5]. Using simple transmission line theory, design expressions for the three-section TLT for three arbitrary operating frequencies were derived. Two non-linear equations were solved simultaneously via an optimization process to obtain the parameters of the transformer. As an application of these TLTs, dual-band two-section TLT and triple-band three-section TLT have been successfully used to design dual-band and triple-band Wilkinson power dividers, respectively, [6-8].

In this paper, the quad-band four-section TLT, which is matched at four arbitrary frequencies  $(f_1, f_2, f_3 \text{ and } f_4)$ for any transforming ratio  $(Z_L/Z_0)$  is designed and analyzed. Four non-linear equations are derived using standard transmission line theory, which are then solved simultaneously using the particle swarm optimization (PSO) technique. The PSO technique is used to find the characteristic impedances and lengths of the first two sections, from which the impedances and lengths of the other sections are obtained using the antimetry conditions [9]. The PSO algorithm is a multiple-agents optimization algorithm that was introduced by Kennedy and Eberhart [10] in 1995 while studying the social behavior of groups of animals and insects such as flocks of birds, schools of fish, and swarms of bees. Recently, this technique found many successful applications in Electromagnetics [11-13]. PSO is similar in some ways to genetic algorithms, but requires less computational bookkeeping and generally fewer lines of code, including the fact that the basic algorithm is very easy to understand and implement. It should be mentioned that other optimization techniques could be used too, but recently, we have been interested in the application of PSO method in the design of different microwave passive elements [14, 15], and antennas [16]. The interested reader can refer to [10-16], and the references therein, for details of the PSO algorithm.

#### II. ANALYSIS AND DESIGN

Figure 1 shows a four-section transmission line transformer (TLT) that will be used to match a purely resistive load  $Z_L$  to a lossless transmission line with characteristic impedance  $Z_0$ . The characteristic impedances of the transmission-line sections are denoted as  $Z_1$ ,  $Z_2$ ,  $Z_3$ , and  $Z_4$ , with physical lengths  $l_1$ ,  $l_2$ ,  $l_3$ , and  $l_4$ , respectively. The problem is to find the lengths and impedances of the four sections such that a perfect match is obtained at four arbitrary frequencies  $f_1$ ,  $f_2$ ,  $f_3$ , and  $f_4$ .

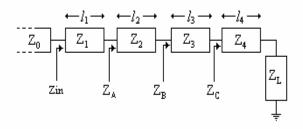


Fig. 1. Four-section quad-band TLT.

Using standard transmission line theory, the input impedance of the four-section TLT is given by,

$$Z_{in} = Z_1 \frac{Z_A + jZ_1 \tan(\beta \ell_1)}{Z_1 + jZ_A \tan(\beta \ell_1)}$$
(1)

where

$$Z_A = Z_2 \frac{Z_B + jZ_2 \tan(\beta \ell_2)}{Z_2 + jZ_B \tan(\beta \ell_2)},$$
(2)

$$Z_{B} = Z_{3} \frac{Z_{C} + jZ_{3} \tan(\beta \ell_{3})}{Z_{3} + jZ_{C} \tan(\beta \ell_{3})},$$
(3)

$$Z_C = Z_4 \frac{Z_L + jZ_4 \tan(\beta \ell_4)}{Z_4 + jZ_L \tan(\beta \ell_4)}.$$
(4)

For perfect matching at specific frequencies, the lengths and impedances should be chosen such that  $Z_{in} = Z_0$  at those frequencies. Imposing this condition on equation (1) and solving for  $Z_A$  gives,

$$Z_{A} = Z_{1} \frac{Z_{0} - jZ_{1} \tan(\beta \ell_{1})}{Z_{1} - jZ_{0} \tan(\beta \ell_{1})}.$$
(5)

Solving equation (2) for  $Z_B$  gives,

$$Z_{B} = Z_{2} \frac{Z_{A} - jZ_{2} \tan(\beta \ell_{2})}{Z_{2} - jZ_{A} \tan(\beta \ell_{2})}.$$
 (6)

Substituting equation (5) in equation (6), gives,

$$Z_{B} = Z_{2} \frac{Z_{1} \frac{Z_{0} - jZ_{1} \tan(\beta \ell_{1})}{Z_{1} - jZ_{0} \tan(\beta \ell_{1})} - jZ_{2} \tan(\beta \ell_{2})}{Z_{2} - jZ_{1} \frac{Z_{0} - jZ_{1} \tan(\beta \ell_{1})}{Z_{1} - jZ_{0} \tan(\beta \ell_{1})} \tan(\beta \ell_{2})}.$$
 (7)

Another equation for  $Z_B$  can be obtained by substituting equation (4) in equation (3), which gives,

$$Z_{B} = Z_{3} \frac{Z_{4} \frac{Z_{L} + jZ_{4} \tan(\beta \ell_{4})}{Z_{4} + jZ_{L} \tan(\beta \ell_{4})} + jZ_{3} \tan(\beta \ell_{3})}{Z_{3} + jZ_{4} \frac{Z_{L} + jZ_{4} \tan(\beta \ell_{4})}{Z_{4} + jZ_{L} \tan(\beta \ell_{4})} \tan(\beta \ell_{3})}.$$
 (8)

Equating the complex equations (7) and (8), we get the following two expressions,

$$\left(\frac{Z_2}{Z_1} - \frac{Z_1}{Z_2}k\right) \tan(\beta \ell_1) \tan(\beta \ell_2)$$

$$+ \left(\frac{Z_3}{Z_1} - \frac{Z_1}{Z_3}k\right) \tan(\beta \ell_1) \tan(\beta \ell_3)$$

$$+ \left(\frac{Z_4}{Z_1} - \frac{Z_1}{Z_4}k\right) \tan(\beta \ell_1) \tan(\beta \ell_4)$$

$$+ \left(\frac{Z_3}{Z_2} - \frac{Z_2}{Z_3}k\right) \tan(\beta \ell_2) \tan(\beta \ell_3)$$

$$+ \left(\frac{Z_4}{Z_2} - \frac{Z_2}{Z_4}k\right) \tan(\beta \ell_2) \tan(\beta \ell_4)$$

$$+ \left(\frac{Z_4}{Z_3} - \frac{Z_3}{Z_4}k\right) \tan(\beta \ell_3) \tan(\beta \ell_4)$$

$$+ \left(\frac{Z_1Z_3}{Z_2Z_4}k - \frac{Z_2Z_4}{Z_1Z_3}\right) \times \left\{ \frac{\tan(\beta \ell_1) \tan(\beta \ell_2)}{\tan(\beta \ell_3) \tan(\beta \ell_4)} \right\} = (1-k),$$
(9)

$$\left(\frac{Z_L}{Z_1} - \frac{Z_1}{Z_0}\right) \tan(\beta \ell_1) + \left(\frac{Z_L}{Z_2} - \frac{Z_2}{Z_0}\right) \tan(\beta \ell_2)$$

$$+ \left(\frac{Z_L}{Z_3} - \frac{Z_3}{Z_0}\right) \tan(\beta \ell_3) + \left(\frac{Z_L}{Z_4} - \frac{Z_4}{Z_0}\right) \tan(\beta \ell_4)$$

$$+ \left(\frac{Z_1 Z_3}{Z_0 Z_2} - \frac{Z_2 Z_L}{Z_1 Z_3}\right) \tan(\beta \ell_1) \tan(\beta \ell_2) \tan(\beta \ell_3)$$

$$+ \left(\frac{Z_1 Z_4}{Z_0 Z_2} - \frac{Z_2 Z_L}{Z_1 Z_4}\right) \tan(\beta \ell_1) \tan(\beta \ell_2) \tan(\beta \ell_4)$$

$$+ \left(\frac{Z_1 Z_4}{Z_0 Z_3} - \frac{Z_3 Z_L}{Z_1 Z_4}\right) \tan(\beta \ell_1) \tan(\beta \ell_3) \tan(\beta \ell_4)$$

$$+ \left(\frac{Z_2 Z_4}{Z_0 Z_3} - \frac{Z_3 Z_L}{Z_2 Z_4}\right) \tan(\beta \ell_1) \tan(\beta \ell_2) \tan(\beta \ell_4)$$

$$+ \left(\frac{Z_2 Z_4}{Z_0 Z_3} - \frac{Z_3 Z_L}{Z_2 Z_4}\right) \tan(\beta \ell_1) \tan(\beta \ell_2) \tan(\beta \ell_3) = 0$$
(10)

where k is the impedance transforming ratio (or the normalized load impedance) defined as  $k=Z_L/Z_0$ .

For a compact size, the characteristics impedances must be monotonically increasing or monotonically decreasing, i.e., they should satisfy one of the following conditions [5],

For 
$$k < 1$$
:  $Z_L < Z_4 < Z_3 < Z_2 < Z_1 < Z_0$   
For  $k > 1$ :  $Z_0 < Z_1 < Z_2 < Z_3 < Z_4 < Z_L$ 

Moreover, since an optimized transformer, in the sense of achieving global minima of the reflection coefficient at the design frequencies, is being designed, it should satisfy the antimetry conditions given as, [9],

$$l_1 = l_4 \text{ and } l_2 = l_3 ,$$
 (11a)

$$Z_1 Z_4 = Z_2 Z_3 = Z_0 Z_{L.}$$
(11b)

It is worth mentioning that the dual-band TLT [3] and the tri-band TLT [5] were found to satisfy these conditions too. Enforcing the above antimetry conditions on the left side of equation (10) gives a zero; that is equation (10) is satisfied if the lengths and the impedances satisfy the antimetry conditions. This validates, to some extent, that indeed the antimetry conditions have to be satisfied. On the other hand, enforcing the antimetry conditions in equation (9), and after some simplification, the following expression is obtained,

$$2a + b \frac{\tan(\beta \ell_1)}{\tan(\beta \ell_2)} + c \frac{\tan(\beta \ell_2)}{\tan(\beta \ell_1)} + d \tan(\beta \ell_1) \tan(\beta \ell_2) + \frac{(k-1)}{\tan(\beta \ell_1) \tan(\beta \ell_2)} = 0$$
(12)

where

$$a = \left(\frac{z_2}{z_1} - \frac{z_1}{z_2}k\right) + \left(\frac{k}{z_1 z_2} - z_1 z_2\right), \quad (13a)$$

$$b = \frac{k}{z_1^2} - z_1^2, \qquad (13b)$$

$$c = \frac{k}{z_2^2} - z_2^2,$$
 (13c)

$$d = \frac{z_1^2}{z_2^2} k - \frac{z_2^2}{z_1^2}.$$
 (13d)

In equation (13), normalized impedances are used where  $z_1=Z_1/Z_0$ , and  $z_2=Z_2/Z_0$ . It is clear that there are four unknowns in equation (12); namely:  $z_1$ ,  $z_2$ ,  $l_1$  and  $l_2$ . Now, equation (12) should be satisfied at the four design frequencies  $f_1$ ,  $f_2$ ,  $f_3$ , and  $f_4$  which can be written as follows:  $f_2=u_1 f_1$ ,  $f_3=u_2 f_1$ , and  $f_4=u_3 f_1$ , where  $u_1$ ,  $u_2$ , and  $u_3$  are any positive real numbers.

At  $f_1$ , we get,

$$2a + b \frac{\tan(\beta_{1}\ell_{1})}{\tan(\beta_{1}\ell_{2})} + c \frac{\tan(\beta_{1}\ell_{2})}{\tan(\beta_{1}\ell_{1})} + d \tan(\beta_{1}\ell_{1}) \tan(\beta_{1}\ell_{2}) + \frac{(k-1)}{\tan(\beta_{1}\ell_{1}) \tan(\beta_{1}\ell_{2})} = 0.$$
(14)

At  $f_2$ , we get,

$$2a + b \frac{\tan(u_{1}\beta_{1}\ell_{1})}{\tan(u_{1}\beta_{1}\ell_{2})} + c \frac{\tan(u_{1}\beta_{1}\ell_{2})}{\tan(u_{1}\beta_{1}\ell_{1})} + d \tan(u_{1}\beta_{1}\ell_{1}) \tan(u_{1}\beta_{1}\ell_{2}) + \frac{(k-1)}{\tan(u_{1}\beta_{1}\ell_{1}) \tan(u_{1}\beta_{1}\ell_{2})} = 0.$$
(15)

At  $f_3$ , we get,

$$2a + b \frac{\tan(u_{2}\beta_{1}\ell_{1})}{\tan(u_{2}\beta_{1}\ell_{2})} + c \frac{\tan(u_{2}\beta_{1}\ell_{2})}{\tan(u_{2}\beta_{1}\ell_{1})} + d \tan(u_{2}\beta_{1}\ell_{1}) \tan(u_{2}\beta_{1}\ell_{2}) + \frac{(k-1)}{\tan(u_{2}\beta_{1}\ell_{1})\tan(u_{2}\beta_{1}\ell_{2})} = 0.$$
(16)

At  $f_4$ , we get,

$$2a+b\frac{\tan(u_{3}\beta_{1}\ell_{1})}{\tan(u_{3}\beta_{1}\ell_{2})}+c\frac{\tan(u_{3}\beta_{1}\ell_{2})}{\tan(u_{3}\beta_{1}\ell_{1})}$$
$$+d\tan(u_{3}\beta_{1}\ell_{1})\tan(u_{3}\beta_{1}\ell_{2})+\frac{(k-1)}{\tan(u_{3}\beta_{1}\ell_{1})\tan(u_{3}\beta_{1}\ell_{2})}=0.$$
(17)

Finally, given k,  $u_1$ ,  $u_2$  and  $u_3$ , the previous four nonlinear equations (14) to (17), need to be solved simultaneously for the four unknowns  $z_1$ ,  $z_2$ ,  $l_1/\lambda_1$  and  $l_2/\lambda_1$ via an optimization process, where  $\lambda_1$  is the wavelength at  $f_1$ .

As mentioned in the introduction, the particle swarm optimization (PSO) technique is used here to solve these four equations. The fitness function is chosen to be the sum of the absolute values of the left sides of equations (14) to (17). Once the four unknowns  $(z_1, z_2, l_1, \text{ and } l_2)$  are obtained, the other four unknowns  $z_3, z_4, l_3$ , and  $l_4$  can be calculated using the antimetry conditions. In all the results presented in the next section, 20 particles are used in the PSO code, and the search is stopped once the value of the fitness function becomes less than 10<sup>-10</sup>. Depending on the initial swarm positions, 1500-2000 iterations were usually needed to reach an acceptable solution. Typically, this took around 15-30 seconds using Pentium-3 PC. The algorithm was run more than once to make sure that it converges to the same solution each time.

#### **III. RESULTS**

Using the approach described in the previous section, several designs have been performed to achieve matching at four arbitrary frequencies. Table 1 shows the obtained results for the case with  $u_1 = 2$ ,  $u_2 = 3$ , and  $u_3 = 4$ , while the impedance ratio k is changed from 0.5 to 10. Figure 2 shows the return loss versus frequency for different values of k. It can be noticed that there is a perfect match at the four design frequencies. From the figure, as expected, one can observe that the response for k and its inverse 1/k are the same. Moreover, from the results in Table 1, we notice that changing the impedance ratio k changes the characteristic impedances, while the lengths of the sections are not affected.

Another case that has been considered is to fix  $u_2$ ,  $u_3$  and k, while changing  $u_1$ . Table 2 includes some results in which  $u_1$  is changed between 1.4 and 2.6, with  $u_2 = 3$ ,  $u_3 = 4$ , k = 2. It can be noticed that as  $u_1$  increases, the impedance and length of the first section decrease, while

the impedance and length of the second section increase. Figure 3 shows the frequency response for some of these cases.

Table 1. Impedances and normalized lengths of a quadband four-section TLT with  $Z_0 = 50 \Omega$ ,  $u_1 = 2$ ,  $u_2 = 3$ , and  $u_3 = 4$ .

k	$Z_1$	$Z_2$	Z <sub>3</sub>	$Z_4$	$l_1/\lambda_1$	$l_2/\lambda_1$
0.5	43.47	37.87	33.01	28.76	0.1	0.1
2	57.51	66.02	75.74	86.94	0.1	0.1
4	66.68	87.51	114.27	149.95	0.1	0.1
6	73.22	103.54	144.86	204.87	0.1	0.1
8	78.56	116.89	171.09	254.56	0.1	0.1
10	83.21	128.58	194.42	300.44	0.1	0.1

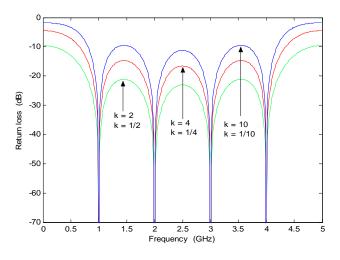


Fig. 2. Return loss of the four-section transformer presented in Table 1 with  $f_1=1$  GHz.

Table 2. Impedances and normalized lengths of a foursection TLT with  $u_2 = 3$ ,  $u_3 = 4$ , k = 2,  $Z_0 = 50 \Omega$ .

$u_1$	$Z_1$	$Z_2$	$Z_3$	$Z_4$
1.4	59.09	63.78	78.39	84.60
1.8	57.98	65.2	76.68	86.24
2.2	57.17	66.69	74.97	87.45
2.6	56.81	67.71	73.85	88.02

$u_1$	$l_1/\lambda_1$	$l_2/\lambda_1$
1.4	0.1493	0.0660
1.8	0.1079	0.0964
2.2	0.0943	0.1019
2.6	0.0858	0.1035

Similarly, one can fix  $u_1$ ,  $u_3$ , and k, while changing  $u_2$ . Table 3 includes some results in which  $u_2$  is changed between 2.4 and 3.6, with  $u_1 = 2$ ,  $u_3 = 4$ , and k = 2. In this case, as  $u_2$  increases,  $Z_1$  and  $l_2$  increase, while  $Z_2$  and  $l_1$ decrease. Figure 4 shows the frequency response for some of these cases.

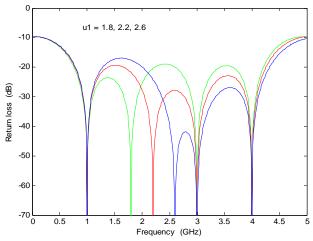


Fig. 3. Return loss of the four-section transformer presented in Table 2 with  $f_1=1$  GHz.

Table 3. Impedances and normalized lengths of a foursection TLT with  $u_1 = 2$ ,  $u_3 = 4$ , k = 2,  $Z_0 = 50 \Omega$ .

$u_2$	$Z_1$	$Z_2$		Z <sub>3</sub>	$Z_4$
2.4	56.77	67.84	73	3.70	88.07
2.8	57.25	66.55	75	5.13	87.33
3.2	57.78	65.56	-76	5.53	86.53
3.6	58.36	64.81	71	7.14	85.67
<i>u</i> <sub>2</sub>	$l_1/\lambda_1$	$l_2/\lambda_1$	L		
2.4	0.1221	0.092	21		
2.8	0.1068	0.097	/4		
3.2	0.0937	0.102	25		
3.6	0.0822	0.107	/4		

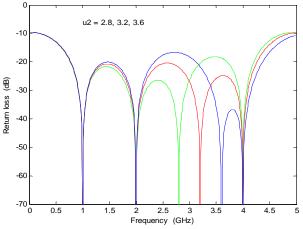


Fig. 4. Return loss of the four-section transformer presented in Table 3 with  $f_1=1$  GHz.

Finally, k,  $u_1$  and  $u_2$  are fixed, and  $u_3$  is changed to different arbitrary values. Table 4 shows some cases in which  $u_3$  is changed between 3.4 and 4.6, with  $u_1 = 2$ ,  $u_2 = 3$ , and k = 2. Figure 5 shows the frequency response for these cases.

Table 4. Impedances and normalized lengths of a foursection TLT with  $u_1 = 2$ ,  $u_2 = 3$ , k = 2,  $Z_0 = 50 \Omega$ .

$u_3$	Z1	Z <sub>2</sub>	Z <sub>3</sub>	$Z_4$
3.4	56.01	65.29	76.58	89.24
3.8	56.95	65.69	76.11	87.77
4.2	58.06	66.49	75.19	86.11
4.6	59.00	68.13	73.38	84.74

$u_3$	$l_1/\lambda_1$	$l_2/\lambda_1$
3.4	0.0987	0.1145
3.8	0.0982	0.1059
4.2	0.1033	0.0928
4.6	0.1140	0.0765

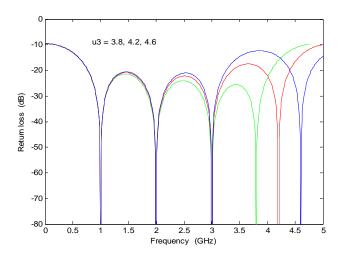


Fig. 5. Return loss of the four-section transformer presented in Table 4 with  $f_1=1$  GHz.

To further validate our analysis, a quad-band foursection microstrip line transformer is designed, fabricated and measured. This transformer is designed to match a load impedance  $Z_L = 100 \ \Omega$  to a 50  $\Omega$  microstrip transmission line at  $f_1 = 0.3 \ \text{GHz}$ ,  $f_2 = 0.6 \ \text{GHz}$ ,  $f_3 = 0.95 \ \text{GHz}$ , and  $f_4 = 1.25 \ \text{GHz}$ . The ideal transmission line sections impedances and lengths are found to be as follows:  $Z_1 = 56.8519 \ \Omega$ ,  $Z_2 = 66.8843 \ \Omega$ ,  $Z_3 = 74.7559 \ \Omega$ ,  $Z_4 = 87.9478 \ \Omega$ ,  $l_1 = l_4 = 69.677 \ \text{degrees}$ ,  $l_2 = l_3 =$ 34.839 degrees, where the electrical lengths refer to  $f_1$ .

Using the software *Ansoft Designer SV* [17], and assuming a 1.6 mm thick FR-4 substrate, the physical lengths and microstrip widths are found to be as follows:

 $\ell_1 = 107.225$  mm,  $\ell_2 = 54.2794$  mm,  $\ell_3 = 54.7366$  mm,  $\ell_4 = 110.761 \text{ mm}$ .  $W_1 = 2.312 \text{ mm}$ ,  $W_2 = 1.697 \text{ mm}$ ,  $W_3$ = 1.343 mm, and  $W_4$  = 0.9157 mm. It should be noted that although the electrical lengths of opposite sections are equal, their physical lengths differ slightly due to the difference in the effective dielectric constant of each section, which depends on the microstrip line width. Figure 6 presents the simulation results obtained using Designer SV, which shows a very good match at the four design frequencies. Using the available PCB facility, this quad-band microstrip line TLT was fabricated, in which a surface mount resistor was used as the load. The overall size of the practical circuit seen in Fig. 7 is  $25 \times 7$  cm. Figure 8 presents the measured return loss, which clearly shows the quad-band impedance matching. Some of the design frequencies are slightly shifted which could be due to losses of the connectors, and the inaccuracies in the widths and lengths of the microstrip line sections.

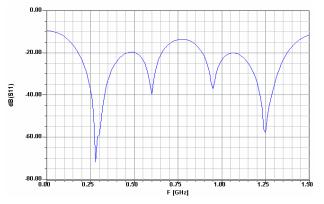


Fig. 6. Simulation results for a quad-band microstrip TLT with a 1.6 mm thick FR-4 substrate ( $\varepsilon_r = 4.6$ ).

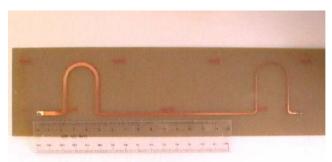


Fig. 7. Photograph of the fabricated quad-band microstrip line TLT. The first and last sections are bent to reduce the total length of the TLT.

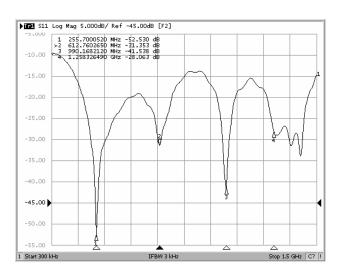


Fig. 8. Measured return loss for the fabricated quad-band microstrip line TLT.

### **IV. CONCLUSIONS**

The contributions presented in this paper can be summarized as follows:

(a) A simple configuration for a quad-band transmission line transformer (TLT) has been proposed which uses four transmission line sections. Using ideal transmission line theory, a single equation, that needs to be satisfied simultaneously at the four design frequencies, has been derived. This equation involved only four unknowns  $(z_1, z_2, l_1/\lambda_1, and l_2/\lambda_1)$  to be solved for.

(b) The particle swarm optimization (PSO) technique, which is drawing much attention at the present time, has been used to design the quad-band TLT by searching for the four parameters  $z_1$ ,  $z_2$ ,  $l_1/\lambda_1$ , and  $l_2/\lambda_1$ . The other four variables  $z_3$ ,  $z_4$ ,  $l_3/\lambda_1$ , and  $l_4/\lambda_1$  were obtained using the antimetry conditions. In effect, the obtained impedances and lengths minimize the reflection coefficient at the four design frequencies.

(c) Finally, to validate the analysis, several quad-band four-section TLTs have been designed. The results were as expected; perfect match at the four frequencies. It has been found that the lengths of the sections do not depend on the transforming ratio k for fixed design frequencies. Moreover, a microstrip line quad-band TLT has been designed, simulated using *Ansoft Designer SV*, fabricated and measured. At the present time, we are investigating the possibility of building a quad-band Wilkinson divider based on the quad-band TLT studied here. Moreover, the design a quad-band transformer that is able to match complex impedances, similar to that presented in [4], will be investigated.

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